

## Lecture 3:

### Initial Data and Conditional Expectation

Last  
Time

Thm 1. Let  $(X_t)_{t \in I}$  be a time homogeneous Markov chain, then the  $m$ -step transition probability

$$P(X_{n+m}=y \mid X_n=x)$$

is the  $m$ -th power of the transition matrix  $P$ , evaluated at the row  $x$  and column  $y$ , i.e.,  $[P^m]_{xy}$ .

Today

1<sup>o</sup>. Remark 1.

$$\begin{aligned} [P^m]_{xy} &= P(X_{n+m}=y \mid X_n=x) \\ &= P(X_m=y \mid X_0=x) \end{aligned}$$

does not depend on  $n$ . This implies time homogeneity

applies not only to  $P(X_{n+1}=y \mid X_n=x) = P(X_1=y \mid X_0=x)$ ,

but also  $P(X_{n+m}=y \mid X_n=x) = P(X_m=y \mid X_0=x)$ .

Remark 2. Also, Theorem 1 implies

$$P(n, n+m) = P^m, \quad \forall n, m \in \mathcal{N}.$$

The left hand side (LHS) does not depend on  $n$  as well. Denote it by  $P(m)$ . That is,

$$P(m) = P^m, \quad \forall m \in \mathcal{N}.$$

Remark 3. Chapman - Kolmogorov equation

$$[P(m+n)]_{xy} = \sum_{z \in X} [P(m)]_{xz} [P(n)]_{zy}, \quad \forall m, n \in \mathcal{N}, \forall x, y \in X.$$

Pf. From Theorem 1,

$$\text{LHS} = [P^{m+n}]_{xy}$$

$$= [P^m \cdot P^n]_{xy}$$

$$= \sum_{z \in X} [P^m]_{xz} [P^n]_{zy}$$

$$= \sum_{z \in X} [P(m)]_{xz} [P(n)]_{zy} = \text{RHS}. \quad \square$$

Recall

If  $A \in M_{m \times n}$ ,  $B \in M_{n \times p}$ ,  
then  $A \cdot B \in M_{m \times p}$ .

Moreover,

$$[AB]_{ij} = \sum_{k=1}^n A_{ik} \cdot B_{kj} \\ = \langle \vec{A}_{i \cdot}, \vec{B}_{\cdot j} \rangle.$$

2°. Ex1. (Gambler's Ruin).

$X_t$  — Gambler's Wallet at time  $t$ .

$N$  : Once  $X_t = N$ , exit game.

$0$  : Once  $X_t = 0$ , exit game.

Flip coins,  $\begin{cases} \text{Head} & \text{with prob. } 0.4 \\ \text{Tail} & \text{with prob. } 0.6 \end{cases}$

If Head,  $X_t = X_{t-1} + 1$ ,  $\forall 0 < X_{t-1} < N$ .  
Tail,  $X_t = X_{t-1} - 1$ ,

$$P(X_t = y | X_{t-1} = x) = \begin{cases} 0.4, & y = x + 1; \forall 0 < x < N. \\ 0.6, & y = x - 1; \\ 0, & \text{otherwise.} \end{cases}$$

$$P(X_t = y | X_{t-1} = x) = \begin{cases} 1, & y = x; \quad x = 0, N. \\ 0, & \text{otherwise.} \end{cases}$$

Q: Is it a Markov chain? Yes.

$$P(X_t = x_t | (X_s)_{s \leq t-1} = (x_s)_{s \leq t-1}) = P(X_t = x_t | X_{t-1} = x_{t-1})$$

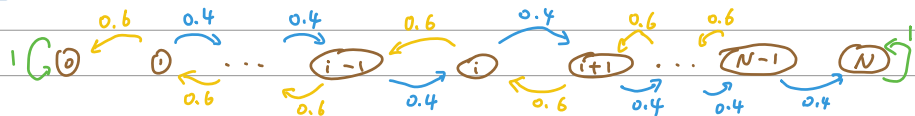
Q: Is it time homogeneous? Yes.

$$P(X_{t+1} = y | X_t = x) = P(X_1 = y | X_0 = x).$$

Q: What's the transition matrix?

$$P = \begin{matrix} & \begin{matrix} 0 & 1 & \dots & i-1 & i & i+1 & \dots & N \end{matrix} \\ \begin{matrix} 0 \\ \vdots \\ i \\ \vdots \\ N \end{matrix} & \begin{bmatrix} 1 & 0 & \dots & 0 & 0 & 0 & \dots & 0 \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 0.6 & 0 & 0.4 & \dots & 0 \\ \vdots & \vdots & & \vdots & \vdots & \vdots & & \vdots \\ 0 & 0 & \dots & 0 & 0 & 0 & \dots & 1 \end{bmatrix} \end{matrix}$$

Q: What's the visualizing chain?



Remark 4. For the case  $N=4$ ,

$$P = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0.6 & 0 & 0.4 & 0 & 0 \\ 0 & 0.6 & 0 & 0.4 & 0 \\ 0 & 0 & 0.6 & 0 & 0.4 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

$$P^2 = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ 0.6 & 0.24 & 0 & 0.16 & 0 \\ 0.36 & 0 & 0.48 & 0 & 0.16 \\ 0 & 0.36 & 0 & 0.24 & 0.8 \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

$P^3, P^4, \dots$

$$\lim_{n \rightarrow \infty} P^n = \begin{matrix} & \begin{matrix} 0 & 1 & 2 & 3 & 4 \end{matrix} \\ \begin{matrix} 0 \\ 1 \\ 2 \\ 3 \\ 4 \end{matrix} & \begin{bmatrix} 1 & 0 & 0 & 0 & 0 \\ \frac{57}{65} & 0 & 0 & 0 & \frac{8}{65} \\ \frac{45}{65} & 0 & 0 & 0 & \frac{20}{65} \\ \frac{27}{65} & 0 & 0 & 0 & \frac{38}{65} \\ 0 & 0 & 0 & 0 & 1 \end{bmatrix} \end{matrix}$$

### 3° Initial Data & Row vectors

Let  $X_0$  be the initial random variable of the time homogeneous Markov chain  $(X_n)_{n \in \mathbb{I}}$ .

Denote by  $0, 1, 2, \dots, |\mathbb{I}|-1$  the elements of  $\mathbb{I}$ .

Denote by  $i_1, i_2, i_3, \dots, i_{|\mathbb{I}|}$  the elements of the state space  $\mathcal{X}$ . Let  $P$  be the transition matrix such that  $P_{jk} = \mathbb{P}(X_1 = i_k | X_0 = i_j)$  the transition probability from the state  $i_j$  to  $i_k$ . Denote by

$$\left. \begin{array}{l} \vec{\mu} \in \mathcal{M}_{1 \times |\mathbb{I}|} \\ P \in \mathcal{M}_{|\mathbb{I}| \times |\mathbb{I}|} \end{array} \right\} \Rightarrow \vec{\mu} P \in \mathcal{M}_{1 \times |\mathbb{I}|}$$

$\mu_j = \mathbb{P}(X_0 = i_j)$  and the row vector

$\vec{\mu} = (\mu_1, \mu_2, \dots, \mu_{|\mathbb{I}|})$  represents the law of  $X_0$ .

Q: What is  $\mathbb{P}(X_1 = i_k)$  ?

$$\begin{aligned} \text{A: } \mathbb{P}(X_1 = i_k) &= \sum_{j=1}^{|\mathbb{I}|} \mathbb{P}(X_1 = i_k, X_0 = i_j) \\ &= \sum_{j=1}^{|\mathbb{I}|} \mathbb{P}(X_1 = i_k | X_0 = i_j) \cdot \mathbb{P}(X_0 = i_j) \\ &= \sum_{j=1}^{|\mathbb{I}|} P_{jk} \cdot \mu_j = [\vec{\mu} P]_k. \end{aligned}$$

#### Multiplication Rule

$$\begin{aligned} \mathbb{P}(A_1, A_2) \\ &= \mathbb{P}(A_1 | A_2) \cdot \mathbb{P}(A_2) \\ &= \mathbb{P}(A_2 | A_1) \cdot \mathbb{P}(A_1). \end{aligned}$$

Q: What is  $\mathbb{P}(X_n = i_k)$  ?

$$\begin{aligned} \text{A: } & \mathbb{P}(X_n = i_k) \\ &= \sum_{j=1}^{|\mathcal{X}|} \mathbb{P}(X_n = i_k, X_0 = i_j) \\ &= \sum_{j=1}^{|\mathcal{X}|} \mathbb{P}(X_n = i_k | X_0 = i_j) \cdot \mathbb{P}(X_0 = i_j) \\ &= \sum_{j=1}^{|\mathcal{X}|} [P^n]_{jk} \cdot \vec{\mu}_j \\ &= [\vec{\mu} P^n]_k. \end{aligned}$$

Prop 1. In sum, once  $\vec{\mu}$  and  $P$  are given, we know the distribution of  $X_n$ ,  $\forall n \in \mathbb{I}$ .

$$\mathbb{P}(X_n = i_k) = [\vec{\mu} P^n]_k.$$

Remark 5. There exists a one-to-one correspondence between  $\{\text{Probability distributions on } \mathcal{X}\}$  and  $\{\nu \in \mathbb{R}^{|\mathcal{X}|} \mid \sum_{j=1}^{|\mathcal{X}|} \nu_j = 1, \nu_j \geq 0, \forall j = 1, 2, \dots, |\mathcal{X}| \} =: \mathcal{M}_1(\mathcal{X})$ .

Here the elements in  $\mathcal{M}_1(\mathcal{X})$  are called probability vectors.

e.g.  $\vec{\mu} = (1, 0, 0, 0) = \delta_1$  is called a "Dirac mass".

#### 4°. Conditional Expectations.

Note: There is a one-to-one correspondence between  
{functions  $f: \mathcal{X} \rightarrow \mathbb{R}$ }  
and  
{vectors  $\vec{f} \in \mathbb{R}^{|\mathcal{X}|}$ }.

e.g. let  $|\mathcal{X}| = 2$ ,  
In the case,  $f: \mathcal{X} \rightarrow \mathbb{R}$   
corresponds to a vector  
 $\vec{f} = \begin{bmatrix} f(i_1) \\ f(i_2) \end{bmatrix} \in \mathbb{R}^2$ .

Notation.  
 $\vec{f} = \begin{bmatrix} f(i_1) \\ f(i_2) \\ \vdots \\ f(i_{|\mathcal{X}|}) \end{bmatrix}$ .

$P(X_m = i_k | X_0 = i_j)$  is a conditional probability.

Let  $f: \mathcal{X} \rightarrow \mathbb{R}$  be a real-valued function on  $\mathcal{X}$ .

Q: What is the expectation of  $f(X_m)$  given  $X_0 = i_j$ ?

$$\begin{aligned} A: \quad & E[f(X_m) | X_0 = i_j] \\ &= \sum_{k=1}^{|\mathcal{X}|} f(X_m = i_k) \cdot P(X_m = i_k | X_0 = i_j) \\ &= \sum_{k=1}^{|\mathcal{X}|} f(i_k) \cdot [P^m]_{jk} \\ &= \sum_{k=1}^{|\mathcal{X}|} \vec{f}_k \cdot [P^m]_{jk} \\ &= [P^m \vec{f}]_j. \end{aligned}$$

## 5° Expectation with initial data

Let  $\vec{\mu}$  be the distribution of  $X_0$ ,  
 $P$  be the transition matrix, and  $f: \mathcal{X} \rightarrow \mathbb{R}$   
be represented by a vector  $\vec{f}$  such that  
 $\vec{f}_k = f(i_k), \forall k = 1, 2, \dots, |\mathcal{X}|$ .

Q: What is the expectation of  $f(X_m)$ ?

$$\begin{aligned} A: & \mathbb{E}[f(X_m) | X_0 \sim \vec{\mu}] \\ &= \sum_{k=1}^{|\mathcal{X}|} f(X_m = i_k) \cdot \mathbb{P}(X_m = i_k | X_0 \sim \vec{\mu}) \\ &= \sum_{k=1}^{|\mathcal{X}|} f(i_k) \cdot [\vec{\mu} P^m]_k \\ &= \sum_{k=1}^{|\mathcal{X}|} \vec{f}_k \cdot [\vec{\mu} P^m]_k \\ &= \vec{\mu} P^m \vec{f} \end{aligned}$$

$1 \times |\mathcal{X}|$  "row vector"  
= law/distribution of  $X_0$

$|\mathcal{X}| \times 1$  "column vector"  
= function on  $\mathcal{X}$ .

This is the end of this lecture !